

**Nonparametric Estimation of Quadratic Functionals
In Gaussian White Noise**

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Nonparametric Estimation of Quadratic Functionals In Gaussian White Noise

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ABSTRACT

Suppose that we observe the process $Y(t)$ from

$$Y(t) = \int_0^t f(u) du + \sigma W(t), \quad t \in [0,1]$$

the optimal rates of convergence (when $\sigma \rightarrow 0$) of quadratic functionals under hyperrectangle type of constraint on unknown function $f(t)$ is addressed, where $W(t)$ is a standard Wiener Process on $[0, 1]$. Specially, the optimal rate of estimating $\int_0^1 [f^{(k)}(x)]^2 dx$ under the hyperrectangle constraint $\Sigma = \{f: x_j(f) \leq n^{-p}\}$ is σ when $p \geq 0.75 + 2k$, and $\sigma^{2 - (4k+1)/(4p-1)}$, when $k + 0.25 < p < 0.75 + 2k$, where $x_j(f)$ is the j th Fourier-Bessel coefficient of unknown function f . The lower bounds are found by applying the hardest 1-dimensional approach as well as testing method. We use the lower bounds to compare how far the lower bounds apart from the upper bounds, not only in rates but also in constant factors, which gives us an idea how efficient the best "unbiased" truncation estimator is in comparison to the possible best estimator. Indeed, with such a comparison, we find the asymptotic minimax estimator for estimating the functional $\int_0^1 f^2(x) dx$ when $p \geq 0.75$. The more general testing bound are also discussed in the current setting.

Key Words and Phrases: Quadratic functionals, Lower bounds, Rates of convergence, Minimax risk, Gaussian white noise, Estimation of bounded squared-mean, testing of hypotheses, Hardest 1-dimensional subproblem, Bayesian approach.

1. Introduction

Suppose the information available for unknown function $f(t)$ is the observation from

$$Y(t) = \int_0^t f(u) du + \sigma W(t), \quad t \in [0, 1] \quad (1.1)$$

with constraint $f(t) \in \Sigma$, a subset of $L^2[0, 1]$, where $W(t)$ is a standard Wiener process on $[0, 1]$. We want to estimate a functional $T(f)$ nonparametrically. The functionals of particular interest in this paper are quadratic functionals, with Σ a hyperrectangle. For example, we want to estimate

$$T(f) = \int_0^1 [f^{(k)}(t)]^2 dt \quad (1.2)$$

where $f^{(k)}(t)$ is the k th derivative of the unknown function $f(t)$. A natural question is how well can we estimate the functional? How well does the best quadratic estimator behave? Ibragimov *et al* (1986) made a start on questions of this kind.

Such a model is apparently the most useful model for studying the properties of non-parametric estimates, as pointed out by Ibragimov *et al* (1986), since the statistical nature of the problem is not complicated. Donoho and Liu (1988) connect such model with non-parametric density estimation by heuristic argument that the information available from an empirical process is almost the same as model (1.1) because the empirical process tends weakly to a Brownian bridge. Indeed, the result of Efroimovich and Pinsker (1982) -- under ellipsoid type of constraint, the best linear estimator of density estimator (found explicitly) is an efficient estimator among all possible estimators -- is motivated by Pinsker's (1980) study of model (1.1). Our results together with recent findings of Bickel and Ritov (1988) also support such a heuristic.

The discretized version of model (1.1) is as follows: fix an orthonormal basis $\{\phi_j(t)\}_{j=1}^{\infty}$ in $L^2[0, 1]$, expand the functional $dY(t)$, $f(t)$, $dW(t)$ on this fixed basis. Then the observation from (1.1) is equivalent to observe their i th coordinate from

$$y_i = x_i + \sigma z_i \quad (i = 1, 2, \dots) \quad (1.3)$$

where y_i, x_i, z_i are the i th coordinate of $dY(t), f(t), dW(t)$ defined by

$$y_i = \int_0^1 \phi_i(t) dY(t), \quad x_i = \int_0^1 \phi_i(t) f(t) dt, \quad z_i = \int_0^1 \phi_i(t) dW(t) \quad (1.4)$$

and the functional $T(f)$ of interest is equivalent to $T(x)$, and constraint Σ is the same as a subset in R^∞ .

The quadratic functionals under consideration are

$$Q(x) = \sum_{i=1}^{\infty} \lambda_i x_i^2 \quad (1.5)$$

with hyperrectangle type of constraint

$$\Sigma = \{x \in R^\infty: |x_i| \leq A_i\} \quad (1.6)$$

To make problem meaningful ($Q(x) < \infty$, for $x \in \Sigma$), assume additionally that

$$\sum_{i=1}^{\infty} \lambda_i A_i^2 < \infty \quad (1.7)$$

Specially, when $\lambda_j = j^{2k}$, and $A_j = j^{-p}$ ($p \geq k + 0.25$), then $Q(x)$ defined by (1.5) is the same as that defined in (1.2) with the smoothness constraint on $f(t)$.

For finding the optimal rates of convergence, mathematically it involves on one hand, to find a lower bound, which says that no estimator can do better than the lower bound, and on the other hand, to find an reasonable estimator to achieve the rate of the lower bound. For the current setting, it is not hard to find an intuitive estimator, which is good enough to allow us to obtain an optimal rate of the convergence.

Finding a lower bound usually involves more mathematical techniques. An usual way to find a minimax lower bound is by assigning an appropriate prior. However, we will show that no intuitive Bayes method works in the current setting. For the setting of nonparametric density estimation, the mathematical background behind the construction of Farrell (1972) and Stone (1980) is that no perfect test, no good estimate even though they didn't state clearly.

The generalization of such an idea is illustrated in Donoho and Liu (1987b,c, 1988).

When T is a linear functional, Donoho and Liu (1987a) shows that when the constraint is convex, balance and symmetric, under quadratic loss, the maximum risk of best linear estimator is no worse than that of the best estimator times 1.34 by using the hardest 1-dimensional trick back to Stein (1956). The optimal rate of the convergence is equivalent to the modulus function defined by

$$b_T(\sigma) = \sup \{ |T(x_1) - T(x_2)| : \|x_1 - x_2\|^2 = \sigma^2, x_1 \in \Sigma, x_2 \in \Sigma \} \quad (1.8)$$

We will see that no matter what kind of functional we want to estimate and what kind of constraint we have, the lower bound $b_T(\sigma)$ is always available to be a lower bound. However, the attainability of the lower bound $b_T(\sigma)$ fails already even for quadratic functionals.

Looking inside of the modulus function defined above, it says by no mean that once we cannot test between x_1 , and x_2 from the observations, then the change of the functional of $T(x)$ is the least mistake we will make for estimation of $T(x)$. For the case that modulus bound doesn't work, one may argue that the pair of $x_1 \in \Sigma$, and $x_2 \in \Sigma$ may not be one of the most difficult pairs of subsets to be tested among all subsets having the same change of the functional based on our observation (1.3). Thus, a more economical and automatic way to formulate a pair of subsets (usually composite) to be tested is that let the change of functional of two sets be at least Δ , and then see how large Δ will be in order to have a good but no perfect test to separate two subsets. The idea of this kind is due to Donoho and Liu (1987c).

Contents of Paper: We begin with finding the best "unbiased" truncation quadratic estimator, and compute its MSE error. Then, we apply the hardest 1-dimensional method to give a lower bound, which shows that when $p \geq q + 0.75$, the best "unbiased" truncation quadratic estimator is quite efficient in asymptotic minimax sense. When $(q + 1)/2 < p < q + 0.75$, the hardest 1-dimensional approach does not give sharp lower bounds. To handle this case, we develop a new lower bound, based on the Bayes risk in testing between two highly composite priors, which shows that the best "unbiased" truncation quadratic estimator gives the optimal

rate in this case. However, the lower bound and upper bound is quite different in the constant factor. Motivated by the testing method, we will suggest how to assign an appropriate prior to give a bigger (possible) lower bound (in constant factor). Finally, we generalize the idea of testing method to more general setting.

2. Quadratic estimators

Let start with the model (1.3). Suppose we observe

$$y = x + \sigma z \quad (2.1)$$

with hyperrectangle type of constraint (1.6). A intuitive class of quadratic estimators to estimate

$$Q(x) = \sum_1^{\infty} \lambda_i x_i^2 \quad (2.2)$$

(where $\lambda_j \geq 0$) is the the class of estimators defined by

$$q_B(y) = y'By + c \quad (2.3)$$

where B is a symmetric matrix, and c is a constant. Simple algebra shows the risk of $q_B(y)$ under quadratic loss is

$$R(B, x) \triangleq E (q_B(y) - Q(x))^2 \quad (2.4)$$

$$= (x'Bx + \sigma^2 \text{tr}B + c - Q(x))^2 + 2\sigma^4 \text{tr}B^2 + 4\sigma^2 x'B^2x \quad (2.5)$$

Following Proposition tells us the class of quadratic estimators with diagonal matrix B is a complete class among all estimators defined by (2.3).

Proposition 2.1: Let D_B be a diagonal matrix, whose diagonal elements are those of B. Then for each symmetric B ,

$$\max_{x \in \Sigma} R(B, x) \geq \max_{x \in \Sigma} R(D_B, x)$$

where Σ is defined by (1.6).

Thus only diagonal matrix B is needed to be considered. For diagonal matrix

$$B = \text{diag}(b_1, b_2, \dots) \quad (2.6)$$

the estimator (2.3) has risk

$$R(B, x) = \left(\sum_1^\infty b_j x_j^2 + \sigma^2 \sum_1^\infty b_j + c - \sum_1^\infty \lambda_j x_j^2 \right)^2 + \sum_1^\infty b_j^2 (2\sigma^4 + 4\sigma^2 x_j^2) \quad (2.7)$$

A natural question is when the estimator (2.3) with B defined by (2.6) converges almost surely.

Following Proposition may state in some standard probability book.

Proposition 2.2: Under model (2.1), $q_B(y)$ converges almost surely for each $x \in \Sigma$ iff

$$\sum_1^\infty b_i (A_i^2 + \sigma^2) < \infty \quad (2.8)$$

Even though for diagonal matrix B , it is hard to find the best quadratic estimator. For the infinite dimensional estimation problem, usually the bias is a one of major contribution to the risk. Thus, we would prefer to use a unique unbiased quadratic estimator

$$\sum_1^\infty \lambda_j (y_j^2 - \sigma^2)$$

but it may not convergence in L^2 , and even it does converge, it may contribute too much on variance. Because of convergence condition (1.7), we know that after certain dimension m (which will go to infinite, as $\sigma \rightarrow 0$), we are not worth to estimate $\sum_m^\infty \lambda_j x_j^2$. Thus, "unbiased" truncation quadratic estimator

$$q_{UT}(y) = \sum_1^m \lambda_j (y_j^2 - \sigma^2) \quad (2.9)$$

is a good candidate for estimating $Q(x)$, and m is chosen to minimize its MSE. For estimator $q_{UT}(y)$ just defined above, the maximum MSE is

$$\max_{x \in \Sigma} R(q_{UT}, x) = \left(\sum_m^\infty \lambda_j A_j^2 \right)^2 + \sum_1^m \lambda_j^2 (2\sigma^4 + 4\sigma^2 A_j^2) \quad (2.10)$$

When $\lambda_j = j^q$ and $A_j = j^{-p}$, ($p > (q + 1)/2$), (2.10) can be simplified a lot. Let's study its asymptotic property as $\sigma \rightarrow 0$. By (2.10), the estimator

$$\sum_1^m j^q (y_j^2 - \sigma^2) \quad (2.11)$$

has its maximum risk

$$R(m) \triangleq \frac{2m^{2q+1}}{2q+1} \sigma^4 (1 + o(1)) + 4\sigma^2 \sum_1^m j^{2q-2p} + \left(\frac{m^{-(2p-q-1)}}{2p-q-1} \right)^2 (1 + o(1))$$

Case I: $(q + 1)/2 < p \leq q + 0.75$.

Choose $m = [c_0 \sigma^{-\frac{4}{4p-1}}]$, where c_0 is specified below. Let

$$g(c) = \frac{2c^{2q+1}}{2q+1} + c^{-2(2p-q-1)/(2p-q-1)^2} \quad (2.12)$$

Then the minimizer of $g(c)$ is $c_0 = (2p - q - 1)^{-\frac{1}{4p-1}}$. Thus, (2.11) is simplified as

$$g(c) \sigma^{4 - \frac{4(2q+1)}{4p-1}} (1 + o(1)) \quad (2.13)$$

and the optimal m is

$$m_0 = [(2p - q - 1)^{-\frac{1}{4p-1}} \sigma^{-\frac{4}{4p-1}}] \quad (2.14)$$

Thus risk of the optimal estimator "unbiased" is

$$g(c_0) \sigma^{4 - \frac{4(2q+1)}{4p-1}} (1 + o(1)) \quad (2.15)$$

Case II: $p > q + 0.75$

The optimal $m_0 = [\sigma^{-\frac{4}{4p-1}}]$, with risk

$$4 \sum_1^\infty j^{2q-2p} \sigma^2 (1 + o(1)) \quad (2.16)$$

Let summarize the result we obtained above

Theorem 1: For $\lambda_j = j^q$ and $A_j = j^{-p}$, ($p > (q + 1)/2$), the best "unbiased" truncation estimated is given by (2.11) with optimal m_0 defined by (2.14) when $(q + 1)/2 < p \leq q + 0.75$, and the maximum risk of the optimal estimator is given by (2.15), and the optimal $m_0 = \lceil \sigma^{-\frac{4}{4p-1}} \rceil$ when $p > q + 0.75$ with the maximum risk given by (2.16).

Note that when $(q + 1)/2 < p \leq q + 0.75$ the rate given above is bigger than σ^2 . In fact, in the next two section, we will show that the "unbiased" truncation estimator is quite efficient in the sense that its risk is quite close to lower bounds, and the rates given above are optimal. Note the when $q = 0$, we will actually prove that the best "unbiased" truncation estimator is asymptotic efficient in minimax sense.

In the following examples, we always assume that the constraint is $\Sigma = \{x: |x_j| \leq j^{-p}\}$.

Example 1: Suppose we want to estimate $T(f) = \int_0^1 f^2(t) dt$ from model (1.1). Let $\{\phi_j(t)\}$ be a fixed orthonormal basis. Then $T(f) = \sum_{j=1}^{\infty} x_j^2$. Thus, the optimal "unbiased" estimator is $\sum_{j=1}^{m_0} \lambda_j (y_j^2 - \sigma^2)$, where

$$m_0 = \begin{cases} \lceil \sigma^{-\frac{4}{4p-1}} \rceil, & \text{if } p > 0.75 \\ \lceil (2p-1)^{-\frac{1}{4p-1}} \sigma^{-\frac{4}{4p-1}} \rceil, & \text{if } 0.5 \leq p \leq 0.75 \end{cases}$$

Moreover, when $p > 0.75$, the estimator is an asymptotic minimax estimator. For $0.5 \leq p \leq 0.75$, the optimal rates are achieved.

Example 2: Let orthonormal basis be $\{\phi_j(t)\} = \{1, \frac{1}{\sqrt{2}} \cos 2\pi j t, \frac{1}{\sqrt{2}} \sin 2\pi j t\}$. We want to estimate

$$T(f) = \int_0^1 [f^{(k)}(t)]^2 dt = (2\pi)^k / 2 \sum_{j=2}^{\infty} j^{2k} x_j^2$$

The optimal "unbiased" estimator is $(2\pi)^k / 2 \sum_{j=2}^{m_0} j^{2k} (y_j^2 - \sigma^2)$, where

$$m_0 = \begin{cases} [\sigma^{-\frac{4}{4p-1}}], & \text{if } p > 2k + 0.75 \\ [(2p - 2k - 1)^{-\frac{1}{4p-1}} \sigma^{-\frac{4}{4p-1}}], & \text{if } k + 0.5 \leq p \leq 2k + 0.75 \end{cases}$$

Moreover, the estimators achieve the optimal rates.

Example 3: (Inverse Problem) Suppose we are interesting in recovering the indirectly observed function $f(t)$ from data of the form (Donoho & MacGibbon (1987))

$$y(u) = \int_0^u \int_0^s K(t, s) f(t) dt ds + \sigma \int_0^u dW, \quad u \in [0, 1]$$

where again W is a Wiener Process and K is known. Let $K: L_2[0, 1] \rightarrow L_2[0, 1]$ have a singular system decomposition (Bertero *et al* (1982)), i.e. a representation

$$Kf = \sum_{i=1}^{\infty} \lambda_i (f, \xi_i) \eta_i$$

where the λ_i are singular values, the $\{\xi_i\}$ and $\{\eta_i\}$ are orthogonal sets in $L_2[0, 1]$. Then the observation is equivalent to

$$y_i = \lambda_i \theta_i + \sigma \varepsilon_i$$

where ε_i are i.i.d. $N(0, 1)$, θ_i is the Fourier-Bessel coefficient of (f, ξ_i) , and y_i is a Fourier-Bessel coefficient of the observed data. Now suppose want to estimate

$$\int_0^1 f^2(t) dt = \sum_{i=1}^{\infty} \theta_i^2 = \sum_{i=1}^{\infty} \lambda_i^{-2} x_i^2$$

where $x_i = \lambda_i \theta_i$. If the non-parametric constraint on θ is a hyperrectangle, then the constraint of x is also a hyperrectangle in R^∞ . Applying Theorem 1, we can get an "optimal" estimator, which achieve the optimal rate. Moreover, we will know roughly how efficient the estimator is if we apply the Table 3.1 and 4.1.

3. Hardest 1-dimensional lower bound

The hardest 1-dimensional trick is suggested by Stein (1956). The idea is to use the difficulty of the hardest 1-dimensional problem as a lower bound of that of nonparametric problem. Thus, for estimation of quadratic functionals (infinite dimensional), we will end up with the difficulty of estimation of θ^2 from observation $Y \sim N(\theta, \sigma^2)$ (1-dimensional).

Let Y be a random variable distributed as $N(\theta, \sigma^2)$, and suppose it is known that $|\theta| \leq \tau$. Let the minimax risk of estimating θ^2 be

$$\rho(\tau, \sigma^2) = \inf_{\delta} \sup_{|\theta| \leq \tau} E_{\theta}(\delta(Y) - \theta^2)^2 \quad (3.1)$$

By definition, it is easy to show that

$$\rho(\tau, \sigma^2) = \sigma^4 \rho(\tau/\sigma, 1) \quad (3.2)$$

For estimation of bounded mean, the quantity

$$\inf_{\delta} \sup_{|\theta| \leq \tau} E_{\theta}(\delta(Y) - \theta)^2 \quad (3.3)$$

has been studied by Casella and Strawderman (1981), Bickel (1982). However $\rho(\tau, \sigma^2)$ behaves much different from the minimax risk of estimation of the bounded mean (3.3). For the purpose of later use, we give the following asymptotic result of $\rho(a, 1)$.

Theorem 2: As $a \rightarrow \infty$,

$$\rho(a, 1) = 4a^2(1 + o(1)) \quad (3.4)$$

Moreover the least favorable prior is the limit (as $n \rightarrow \infty$) of the prior density of

$$g_n(\theta, a) = \frac{(2n+1)\theta^{2n}}{2a^{2n+1}} 1_{(|\theta| \leq a)} \quad (3.5)$$

Now we are ready to find a lower bound by using the hardest 1-dimensional trick. Fix a point $x \in \Sigma$. Let $x_t = tx$, $t \in [-1, 1]$, be a line segment passing the origin. Then the problem of estimating of $Q(x)$ in $\{x_t\}$ is just that of estimating

$$\theta^2 = Q(tx) = t^2 Q(x) \quad (3.6)$$

from observation

$$y = tx + \sigma z$$

where z is normal with mean 0 and variance identity, and t is unknown to be estimated. As $(y, x) \sim N(t\|x\|^2, \sigma^2\|x\|^2)$ is a sufficient statistics for t , the observation available for estimation t or θ is equivalent to that from $\frac{\sqrt{Q(x)}}{\|x\|^2} (y, x) \sim N(\theta, \frac{Q(x)}{\|x\|^2} \sigma^2)$. Thus the minimax risk of estimation θ^2 in the problem is

$$\rho(\sqrt{Q(x)}, \frac{Q(x)}{\|x\|^2} \sigma^2) \quad (3.7)$$

according to our notation. By (3.2),

$$\rho(\sqrt{Q(x)}, \frac{Q(x)}{\|x\|^2} \sigma^2) = \frac{Q(x)^2 \sigma^4}{\|x\|^4} \rho(\|x\| / \sigma, 1) \quad (3.8)$$

But, the minimax risk of estimation $Q(x)$ is at least as difficulty as that of estimation θ^2 . Consequently,

$$\begin{aligned} & \inf_{\delta} \sup_{x \in \Sigma} E_x (\delta(y) - Q(x))^2 \\ &= \inf_{\delta} \sup_{x \in \Sigma} \sup_{|t| \leq 1} E_{tx} (\delta(y) - t^2 Q(x))^2 \\ &\geq \sup_{x \in \Sigma} \inf_{\delta} \sup_{|t| \leq 1} E_{tx} (\delta(y) - \theta^2)^2 \\ &\geq \sup_{x \in \Sigma} \frac{Q^2(x) \sigma^4}{\|x\|^4} \rho(\|x\| / \sigma, 1) \end{aligned}$$

In conclusion,

Theorem 3: The minimax risk of estimation $Q(x)$ from observation (2.1) is at least

$$\sup_{x \in \Sigma} \frac{Q(x)^2 \sigma^4}{\|x\|^4} \rho(\|x\| / \sigma, 1) \quad (3.9)$$

and as $\sigma \rightarrow 0$, the minimax lower bound is at least

$$\sup_{x \in \Sigma, \|x\| > 0} \frac{4Q^2(x)}{\|x\|^2} \sigma^2 (1 + o(1)) \quad (3.10)$$

Comparing the lower bound and upper bound given by (2.16), when $p \geq q + 0.75$ the rate σ^2 is the optimal one. When $p = 0$, the best truncation is the asymptotic minimax estimator. How close is the upper bound to lower bound? By (2.16) and (3.10), as $\sigma \rightarrow 0$

$$\frac{\text{Lower Bound}}{\text{Upper Bound}} \geq \frac{C_{2p-q}^2}{C_{2p} C_{2p-2q}} \quad (3.11)$$

where $C_r = \sum_{j=1}^{\infty} j^{-r}$ can be calculated numerically. Following table shows the result:

Table 3.1: Comparison of the lower bound and upper bound
 $p = 1 + 1 + 0.5 i$

	i=1	i=2	i=3	i=4	i=5	i=6	i=7	i=8
q=0.0	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000
=0.5	0.976	0.991	0.996	0.998	0.999	1.000	1.000	1.000
=1.0	0.940	0.977	0.990	0.995	0.998	0.999	0.999	1.000
=1.5	0.910	0.963	0.984	0.992	0.996	0.998	0.999	0.999
=2.0	0.887	0.952	0.979	0.990	0.995	0.998	0.999	0.999
=2.5	0.871	0.944	0.975	0.988	0.995	0.997	0.998	0.999
=3.0	0.859	0.938	0.972	0.987	0.994	0.997	0.998	0.999
=3.5	0.851	0.934	0.970	0.986	0.993	0.996	0.998	0.999
=4.0	0.845	0.931	0.968	0.985	0.993	0.996	0.998	0.999
=4.5	0.842	0.929	0.967	0.984	0.992	0.996	0.998	0.999
=5.0	0.839	0.928	0.966	0.984	0.992	0.996	0.998	0.999

4. Testing of the vertices of hypercube

Note that when $(q + 1)/2 \leq p < q + 0.75$, the upper bound (2.15) is not at the rate of σ^2 , and consequently, the hardest 1-dimensional lower bound (3.10) is much smaller. We may wonder whether 1-dimensional bounds cannot capture the difficulty of estimating quadratic functionals or else the best "unbiased" truncation estimator is not a good estimator in this case. Indeed, we will construct a bigger lower bound, which says the best "unbiased" truncation estimator gives the optimal rate.

The idea of the construction is as follows: take a largest hypercube of dimensional n (which depends on σ) in the hyperrectangle, and assign probability $\frac{1}{2^n}$ to each vertices, and then test them against the origin. When no perfect test exists (by choosing some critical value n , depending on σ), the difference in functional values at two hypercubes supplies a lower bound. The approach we use is related to one of Ibragimov *et al* (1986), who, however use hypersphere rather than hyperrectangle.

To carry out the idea, let's formulate testing problem

$$H_0: x_i = 0, \leftrightarrow H_1: x_i = \pm t_n \ (i=1, \dots, n), \ 0 \ (i > n), \quad (4.1)$$

i.e. we want to test whether the observation y_i from H_0 or H_1 , which is specified as follows:

$$H_0: y_i \sim N(0, \sigma^2) \ (i = 1, \dots, n) \leftrightarrow \quad (4.2)$$

$$H_1: y_i \sim \frac{1}{2} [\phi(y, t_n, \sigma) + \phi(y, -t_n, \sigma)], \ (i = 1, \dots, n).$$

where $\phi(y, t, \sigma)$ is the density function of $N(t, \sigma^2)$. The result of the testing can be summarized as follows:

Lemma 4.1: The sum of type I and type II error of the best testing procedure is

$$2 \Phi\left(-\frac{\sqrt{n} (t_n / \sigma)^2}{\sqrt{8}}\right)(1 + o(1)) \quad (4.3)$$

if $n^{1/2} (t_n / \sigma)^2 \rightarrow c$, where $\Phi(\cdot)$ is the probability function of a standard normal distribution.

Now we are ready to derive a lower bound. Let

$$r_n = |Q(H_1) - Q(H_0)|/2 = t_n^2 \sum_1^n \lambda_j / 2 \quad (4.4)$$

be the half of change of the functional. For any estimator $T(y)$, the minimax risk under quadratic loss is

$$\begin{aligned} & \sup_{x \in \Sigma} E_x (T(y) - Q(x))^2 \\ & \geq \frac{1}{2} [E_0 (T(y) - Q(x))^2 + E_1 (T(y) - Q(x))^2] \\ & \geq \frac{1}{2} r_n^2 [P_0 (|T(y)| \geq r_n) + P_1 (|T(y) - Q(x)| \geq r_n)] \\ & \geq \frac{1}{2} r_n^2 [P_0 (|T(y)| \geq r_n) + P_1 (|T(y)| \leq r_n)] \\ & \geq r_n^2 \Phi\left(-\frac{\sqrt{n} (t_n / \sigma)^2}{\sqrt{8}}\right)(1 + o(1)) \end{aligned} \quad (4.5)$$

where E_0 and E_1 mean that take the expectation under H_0 and H_1 , respectively.

The last inequality holds because we can view the second term of (4.5) as sum of type I error and type II error, which is no smaller than that of best test procedure given by Lemma 4.1. Thus, take n such that the last term is bounded away from 0, then r_n^2 is the order of the lower bound.

Theorem 4: Suppose that A_j is increasing in j , when j is large. Let n_σ be the largest number of the equation

$$\sqrt{n} (A_n / \sigma)^2 \leq c$$

Then, for any estimator $T(y)$, the maximum risk of estimating $Q(x)$ is no smaller than

$$\sup_c \left\{ \frac{\Phi(-c/\sqrt{8})}{4} \left(\sum_1^{n_\sigma} \lambda_j \right)^2 A_{n_\sigma}^4 \right\} (1 + o(1)) \quad (as \ \sigma \rightarrow 0). \quad (4.6)$$

Moreover,

$$\sup_{x \in \Sigma} P_x \{ |T(y) - Q(x)| \geq \frac{(\sum_1^{n_\sigma} \lambda_j) A_{n_\sigma}^2}{2} \} \geq \Phi(-\frac{c}{\sqrt{8}}) (1 + o(1))$$

and for any symmetric increasing loss function $l(\cdot)$,

$$\sup_{x \in \Sigma} E_x \left[l\left(\frac{2|T(y) - Q(x)|}{\sum_1^{n_\sigma} \lambda_j A_{n_\sigma}^2}\right) \right] \geq l(1) \Phi(-\frac{c}{\sqrt{8}}) + o(1)$$

When $A_j = j^{-p}$ and $\lambda_j = j^q$, we can calculate the rate in Theorem 4 explicitly.

Corollary 4.1: When $A_j = j^{-p}$ and $\lambda_j = j^q$, for any estimator the minimax risk under quadratic loss is no better than

$$\xi_{p,q} \sigma^{4 - \frac{4(2q+1)}{4p-1}} (1 + o(1))$$

Moreover, for any estimator $T(y)$,

$$\sup_{x \in \Sigma} P_x \{ |T(y) - Q(x)| \geq c^{1 - \frac{2q+1}{4p-1}/(2(q+1))} \sigma^{2 - \frac{2(2q+1)}{4p-1}} \} \geq \Phi(-\frac{c}{\sqrt{8}}) (1 + o(1))$$

where

$$\xi_{p,q} = \sup_{c > 0} c^{2 - \frac{4q+2}{4p-1}} \Phi(-\frac{c}{\sqrt{8}}) / (4(q+1)^2)$$

When $(q+1)/2 \leq p < q+0.75$, by comparing the lower bound and upper bound given in section 2, again we show that the best "unbiased" truncation estimator gives the optimal rate. Following table shows how close the lower bound and the upper bound are.

Table 4.1: Comparison of the lower bound and the upper bound

q = 0		q = 1		q = 2		q = 3		q = 4	
p =	ratio	p =	ratio	p =	ratio	p =	ratio	p =	ratio
0.55	0.0333	1.15	0.0456	1.75	0.0485	2.35	0.0495	2.95	0.0499
0.60	0.0652	1.30	0.0836	2.00	0.0864	2.70	0.0864	3.40	0.0858
0.65	0.0949	1.45	0.1159	2.25	0.1170	3.05	0.1153	3.85	0.1132
0.70	0.1218	1.60	0.1431	2.50	0.1419	3.40	0.1383	4.30	0.1345

where $ratio = \sqrt{\frac{\text{lower bound by testing method}}{\text{upper bound by } q_{UT}(y)}}$

The above table tells us that there is a large discrepancy at the level of constants between the upper and lower bounds. It appears to us that the hypersphere bound of Ibragimov *et al* (1986) would not give a lower bound of the same order as we are able to get via hypercubes.

5. Bayes Method

Often we use Bayes method to find a minimax lower bound. However, as mentioned in the introduction, the *intuitive* Bayes method gives too small lower bound in the case of $(q + 1)/2 \leq p < q + 0.75$. By *intuitive* Bayes method, we mean that assign prior uniformly on the hyperrectangle, which is equivalent to say that independently assign prior uniformly on each coordinate, or more generally assign prior $x_j \sim \pi_j(\theta)$ independently. Mathematically, assigning the prior in this way does not include the interaction term (which has order n^2 terms) and hence give a smaller lower bound. To see this, let $\rho_{\pi_j}(j^{-P}, \sigma)$ be the Bayes risk of estimation θ^2 from $Y \sim N(\theta, \sigma^2)$ knowing $|\theta| \leq j^{-P}$ with prior π_j . Let $\hat{\delta}(y) = E(\sum_1^{\infty} j^q x_j^2 | y)$ be the Bayes solution of the problem. By independent assumption of prior,

$$\hat{\delta}(y) = \sum_1^{\infty} j^q E(x_j^2 | y_j)$$

Then the Bayes risk is

$$\begin{aligned}
 E_{\pi} E_x (\delta(y) - \sum_1^{\infty} j^q x_j)^2 &= \sum_1^{\infty} j^{2q} \rho_{\pi_j}(j^{-p}, \sigma) \\
 &\leq \sum_1^n j^{2q} \rho_{\pi_j}(j^{-p}, \sigma^2) + \sum_{n+1}^{\infty} j^{2q-4p}
 \end{aligned} \tag{5.1}$$

because the Bayes risk is no larger than the maximum risk of estimator 0. As Bayes risk is no bigger than the minimax risk, by Theorem 2, the last quantity is no bigger than

$$\begin{aligned}
 &\sum_1^n j^{2q} \rho_{\pi_j}\left(\frac{j^{-p}}{\sigma}, 1\right) \sigma^4 + O(n^{-4p+2q+1}) \\
 &\leq O(n^{2q-2p+1} \sigma^2) + O(n^{-4p+2q+1}) \\
 &= \max(O(\sigma^2), O(\sigma^{4-\frac{2q+1}{p}})) \\
 &= o(\sigma^{4-\frac{4(2q+1)}{4p-1}}) \quad (\text{when } (q+1)/2 < p < q+0.75)
 \end{aligned}$$

by choosing $n = \sigma^{-\frac{1}{p}}$.

To find a bigger lower bound, motivated by the testing method, take a largest n dimensional hypercube in Σ . Assign prior $\pi(x)$ on the diagonal line segments starting from the origin uniformly, with probability $\frac{1}{2^n}$ to each line segment of the hypercube.

Mathematically, assigning the prior in this way can be reduced to find the Bayes risk of the estimating θ^2 based on the n i.i.d. observations y_i having density

$$y_i \sim \frac{1}{2}(\phi(\theta, 1) + \phi(-\theta, 1))$$

with prior $\pi(\theta)$ is uniformly distributed on $[0, t_n]$, and denote the Bayes risk by $B(t_n, n)$, where $\phi(\theta, 1)$ is the density of normal distribution with mean θ and variance 1. Then, a minimax lower bound of estimating $Q(x)$ is at least as big as the Bayes risk, i.e. no smaller than the quantity

$$\begin{aligned} \min_{\delta(y)} \max_{|\theta| \leq A_n} E(\delta(y) - \sum_1^n \lambda_j \theta^2)^2 \\ \geq (\sum_1^n \lambda_j)^2 \sigma^4 B(A_n/\sigma, n) \end{aligned}$$

We believe that for the case $A_n = n^{-p}$, and $\lambda_j = j^q$ by choosing suitable dimension $n = \lceil (c\sigma)^{-\frac{4}{4p-1}} \rceil$, the lower bound might be improved. We are not going to pursue that here.

6. General testing lower bound

In this section, we will generalize the testing bound to more general setting, which applies to all functionals to be estimated and any kind of constraint. Suppose we have observation from (1.3), and want to estimate $T(x)$ knowing $x \in \Sigma$. Then no estimator can estimate $T(x)$ faster than the modulus bound defined by (1.8).

Theorem 5: For any estimator $\delta(y)$ from observation (1.3),

$$\sup_{x \in \Sigma} E_x (\delta(y) - T(x))^2 \geq \sup_c \Phi(-c/2) b_T^2(c\sigma)/4$$

where b_T is defined by (1.8).

Remark: When the hardest 1-dimensional lower bound and modulus bound both give the correct rates for estimating quadratic functional ($p \geq q + 0.75$), the modulus bound gives a smaller constant factor. In fact, by Cauchy-Schwartz inequality,

$$b_T(\epsilon) \leq 2\sqrt{\sum j^{2q} j^{-2p}} \epsilon = 2\sqrt{C_{2(p-q)}} \epsilon \quad (p - q > 0.5)$$

and

$$\frac{\text{Modulus bound}}{\text{1-dim bound}} \leq \frac{\sup_c [\Phi(-c/2) c^2] C_{2(p-q)} C_{2p}}{4 C_{2p-q}^2} = 0.167 \times \frac{C_{2(p-q)} C_{2p}}{C_{2p-q}^2},$$

where $C_r = \sum_1^\infty j^{-r}$. The second is evaluated numerically in Table 3.1. For $p=0$, the last term

is no bigger than 0.167 and sometimes even much worse, if we evaluate both bounds more

carefully.

Applying the testing trick in section 4, we can give a more general result which allow us to judge whether the modulus lower bound is too small or not. To state the result, without loss of generality, assume that $T(0) = 0$. Let l_n be the length of the largest n -dimensional hypercube in Σ , with $l_n > 0$ and $l_n \rightarrow 0$, and N_σ be the largest integer such that

$$n^{0.25} l_n \geq \sigma$$

Theorem 6: Under the above notations, assume that in the neighborhood of origin, $|T(x)| \geq Q(x)$, which is symmetric in each argument. Then the rate of $Q(x_\sigma)$ is a lower rate, in the sense that no estimator can estimate $T(x)$ faster than that of $Q(x_\sigma)$ (as $\sigma \rightarrow 0$), where $x_\sigma = (\sigma, \dots, \sigma, 0, 0, \dots)/N_\sigma^{0.25}$ with N_σ non-zero elements.

If moreover $b_T(c\sigma)/Q(x_\sigma) \rightarrow 0$ for each c . Then modulus bound $b_T(c\sigma)$ does not give an achievable lower rate under quadratic loss, where b_T is defined by (1.8).

As mentioned in the introduction, 2-points testing bound may not be the best pair to be tested. To give a more powerful lower bound, let $\Sigma_{T \leq t} = \{x \in \Sigma: T(x) \leq t\}$ and $\Sigma_{T \geq t + \Delta}$ defined similarly be the two subsets to be tested. Let $\text{conv}(\Sigma_{T \geq t + \Delta})$ be the convex hull of $\Sigma_{T \geq t + \Delta}$ in the space of distributions, and define $\text{conv}(\Sigma_{T \leq t})$ similarly. Le Cam (1985) shows minimax risk of the sum of type I and type II error of testing

$$H_0: x \in \Sigma_{T \geq t + \Delta} \leftrightarrow H_1: x \in \Sigma_{T \leq t} \quad (6.1)$$

is just the maximum testing affinity of the hardest pair in $\text{conv}(\Sigma_{T \geq t + \Delta})$ and $\text{conv}(\Sigma_{T \leq t})$, and denote it by $\pi(\text{conv}(\Sigma_{T \geq t + \Delta}), \text{conv}(\Sigma_{T \leq t}))$, i.e.

$$\begin{aligned} & \pi(\text{conv}(\Sigma_{T \geq t + \Delta}), \text{conv}(\Sigma_{T \leq t})) = \\ & \min_{0 \leq \phi \leq 1} \max_{x \in \Sigma_{T \geq t + \Delta} \cup \Sigma_{T \leq t}} (E_x \phi(y) + E_x(1 - \phi(y))). \end{aligned} \quad (6.2)$$

The sum of type I and type II of the most difficult subsets to is tested be

$$\alpha_T(\Delta, \sigma) = \sup_t \pi(\text{conv}(\Sigma_{T \geq t + \Delta}), \text{conv}(\Sigma_{T \leq t})) \quad (6.3)$$

Hence the largest change of the functional Δ of the pair that we cannot test

$$\Delta_T(\alpha, \sigma) = \sup\{\Delta: \alpha_T(\Delta, \sigma) \geq \alpha\} \quad (6.4)$$

Then, we have following theorem, which generalizes all kinds of testing lower bound given above.

Theorem 7: For any estimator $\delta(y)$,

$$\inf_{\delta} \sup_{x \in \Sigma} P_x\{|\delta(y) - T(x)| \geq \Delta_T(\alpha, \sigma)/2\} \geq \alpha/2$$

and for any symmetric increasing loss $l(t)$, the minimax risk lower bound is given

$$\inf_{\delta} \sup_{x \in \Sigma} E_x l\left(\frac{2(\delta(y) - Q(x))}{\Delta_T(\alpha, \sigma)}\right) \geq l(1) \frac{\alpha}{2}$$

7. Proofs

Proof of Proposition 2.1:

For any subset $S \subset \{1, 2, \dots\}$, let prior μ^S be the probability measure of independently assigning $x_j = \pm A_j$ with probability $\frac{1}{2}$ each, for $j \in S$ and assigning probability 1 to the point 0 for $j \notin S$. Then by the Jensen's inequality,

$$\begin{aligned} & \max_{x \in \Sigma} R(B, x) \\ & \geq \max_S E_{\mu^S} R(B, x) \\ & \geq \max_S \{ (E_{\mu^S}(x' B x) + \sigma^2 \text{tr} B + c - E_{\mu^S}[Q(x)])^2 + 2\sigma^4 \text{tr} B^2 + 4\sigma^2 E_{\mu^S}(x' B^2 x) \}. \end{aligned} \quad (7.1)$$

Let $D_A = E_{\mu^S}(xx')$, which is a diagonal matrix. Simple calculation shows that

$$E_{\mu^S}(x' B x) = \text{tr}(B D_A) = \text{tr}(D_B D_A)$$

$$E_{\mu^S}(x' B^2 x) = \text{tr}(B^2 D_A) \geq \text{tr}(D_B)^2 D_A$$

$$\text{tr} B^2 = \text{tr} B' B = \text{tr} D_B^2$$

Thus by (7.1) and the last 3 display,

$$\max_{x \in \Sigma} R(B, x) \geq \max_S E_{\mu^S} R(D_B, x) = \max_{x \in \Sigma} R(D_B, x)$$

The last equality holds because (2.7) is convex in x_j^2 , and consequently attains its maximum at either $x_j^2 = 0$ or $x_j^2 = A_j^2$.

Proof of Proposition 2.2

Sufficiency follows from the monotone convergence theorem:

$$Eq_B(x) = \sum_1^{\infty} b_i (x_i^2 + \sigma^2) + c < \infty$$

Suppose that (2.3) convergence a.s. for each $x \in \Sigma$, then according to Kolmogrov 3-series theorem,

$$\sum_1^{\infty} P \{ b_i y_i^2 \geq 1 \} < \infty \quad (7.2)$$

$$\sum_1^{\infty} E b_i y_i^2 1_{(b_i y_i^2 \leq 1)} < \infty \quad (7.3)$$

As the distribution of y_i is normal, it is easy to check that

$$E y_i^4 \leq 3(E y_i^2)^2$$

Thus by Cauchy-Schwartz inequality,

$$\begin{aligned} & E b_i y_i^2 1_{(b_i y_i^2 \geq 1)} \\ & < \sqrt{3} E b_i y_i^2 P \{ b_i y_i^2 \geq 1 \} \\ & = o(E b_i y_i^2) \end{aligned} \quad (7.4)$$

Hence the assertion follows from (7.3) and (7.4).

Proof of Theorem 2

Let the prior distribution of θ is $g_n(\theta, a)$ defined by (3.5), for fixed n . Then the posterior density of θ given Y is

$$\frac{\theta^{2n} \exp(-(y - \theta)^2 / 2) \mathbf{1}_{(|\theta| \leq a)}}{\int_{-a}^a \theta^{2n} \exp(-(y - \theta)^2 / 2) d\theta} \quad (7.5)$$

Thus, the Bayes solution under quadratic loss is

$$E(\theta^2 | y) = \frac{\int_{-a}^a \theta^{2n+2} \exp(-(y - \theta)^2 / 2) d\theta}{\int_{-a}^a \theta^{2n} \exp(-(y - \theta)^2 / 2) d\theta} \\ \triangleq y^2 + \delta_a(y) \quad (7.6)$$

Now, the risk of the Bayes estimate is

$$E(y^2 + \delta_a(y) - \theta^2)^2 \\ = 4\theta^2 + 3 + E\delta_a^2(\epsilon + \theta) + 4E\epsilon\delta_a(\epsilon + \theta) + 2E\epsilon^2\delta_a(\epsilon + \theta)$$

where $\epsilon \sim N(0, 1)$. Thus, the Bayes risk is

$$4 \frac{2n+1}{2n+3} a^2 + E\delta_a^2(\epsilon + \theta) + 4E\epsilon\delta_a(\epsilon + \theta) + 2E\epsilon^2\delta_a(\epsilon + \theta) + 3 \quad (7.7)$$

where E represents taking the expectation over $\epsilon \sim N(0, 1)$, and $\theta \sim g_n(\theta, a)$.

We will prove that

$$E\delta_a^2(\epsilon + \theta) = o(a^2) \quad (7.8)$$

Suppose (7.8) is true, then By Cauchy-Schwartz inequality,

$$E \epsilon \theta \delta_a(\epsilon + \theta) \leq (E \theta^2 E \epsilon^2)^{1/2} (E \delta_a^2(\epsilon + \theta))^{1/2} = o(a^2)$$

Thus, by (7.7), the Bayes risk is

$$4 \frac{2n+1}{2n+3} a^2(1 + o(1)) \rightarrow 4a^2(1 + o(1)), \text{ (as } n \rightarrow \infty)$$

Consequently,

$$\rho(a, 1) \geq 4a^2(1 + o(1))$$

On the other hand,

$$\sup_{|\theta| \leq a} E_{\theta}(Y^2 - \theta^2)^2 = 4a^2 + 3$$

We conclude that

$$\rho(a, 1) = 4a^2(1 + o(1))$$

Now, we have to check (7.8). By definition of (7.6) and integration by parts,

$$\delta_a(y) = \frac{\int_{-a}^a \theta^{2n} (\theta^2 - y^2) \exp(-(y - \theta)^2 / 2) d\theta}{\int_{-a}^a \theta^{2n} \exp(-(y - \theta)^2 / 2) d\theta} \quad (7.9)$$

$$= -\delta_1(y) + \delta_2(y) + (2n+1) + 2n\delta_3(y) \quad (7.10)$$

where

$$\delta_1(y) = a^{2n} (y + a) \exp(-(y - a)^2 / 2) / I \quad (7.11)$$

$$\delta_2(y) = a^{2n} (y - a) \exp(-(y + a)^2 / 2) / I \quad (7.12)$$

$$\delta_3(y) = y \int_{-a}^a \theta^{2n-1} \exp(-(y - \theta)^2 / 2) d\theta / I \quad (7.13)$$

$$I = \int_{-a}^a \theta^{2n} \exp(-(y - \theta)^2 / 2) d\theta \quad (7.14)$$

Thus, to prove (7.8), we need only to prove

$$E \delta_j^2(y) = o(a^2), \quad (j = 1, 2, 3)$$

which will be proved by following three Lemmas, where $y \stackrel{d}{=} \theta + \varepsilon$

Lemma 2.1: Under the above notations, $E \delta_1^2(y) = o(a^2)$

Proof: When $y \leq a - 1$, and a is large,

$$\begin{aligned} I &\geq (a - 1)^{2n} \int_{a-1}^a \exp(-(y - \theta)^2 / 2) d\theta \\ &\geq (a - 1)^{2n} \exp(-(y - a)^2 / 2) \\ &\geq \frac{1}{2} a^{2n} \exp(-(y - a)^2 / 2) \end{aligned}$$

Thus, on the set $\{y: y \leq a - 1\}$,

$$\delta_1^2(y) \leq 4(a + y)^2 \leq 16a^2$$

Consequently, by Lebesgue's dominated convergence theorem,

$$E \delta_1^2(y) \mathbf{1}_{(y \leq a - 1)} = o(a^2) \quad (7.15)$$

On the set $\{a - 1 \leq y \leq a\}$, we have

$$\begin{aligned} I &\geq \int_{a-1}^a \theta^{2n} \exp(-(y - \theta)^2 / 2) d\theta \\ &> e^{-0.5} (a - 1)^{2n} \\ &\geq 0.5 e^{-0.5} a^{2n} \exp(-(y - a)^2 / 2) \end{aligned} \quad (7.16)$$

Thus, by (7.16)

$$\begin{aligned}
 & E \delta_1^2(y) \mathbf{1}_{(a-1 \leq y \leq a)} \\
 & \leq 16e a^2 P \{a-1 \leq y \leq a\} = o(a^2)
 \end{aligned} \tag{7.17}$$

When $y > a$,

$$\begin{aligned}
 I & \geq (a-1)^{2n} \int_{a-1}^a \exp(-(y-\theta)^2/2) d\theta \\
 & \geq \frac{(a-1)^{2n}}{y-a+1} [\exp(-(y-a)^2/2) - \exp(-(y-a+1)^2/2)] \\
 & \geq \frac{a^{2n}}{2(y-a+1)} (1 - e^{-0.5}) \exp(-(y-a)^2/2)
 \end{aligned}$$

Hence,

$$\begin{aligned}
 & E \delta_1^2(y) \mathbf{1}_{(y > a)} \\
 & \leq 4(1 - e^{-0.5})^{-2} E (y-a+1)^2 (y+a)^2 \mathbf{1}_{(y > a)}
 \end{aligned} \tag{7.18}$$

Note that

$$P \{y > a\} \leq P \{a - a^{0.25} < \theta\} + P \{a^{0.25} < \epsilon\} = O(a^{-0.75}) \tag{7.19}$$

Note also that

$$\begin{aligned}
 P \{y > a + a^{0.25}\} & \leq P \{\epsilon > a^{0.25}\} \\
 & = O(a^{-0.25}) \exp(-\sqrt{a}/2)
 \end{aligned} \tag{7.20}$$

By the easily checking fact that

$$E |y|^m = O(a^m)$$

and Cauchy-Schwartz inequality,

$$\begin{aligned}
 & E \delta_1^2(y) \mathbf{1}_{(y > a)} \\
 & \leq 4(1 - e^{-0.5})^2 [E (y-a+1)^2 (y+a)^2 \mathbf{1}_{(a^{0.25} + a \geq y > a)}]
 \end{aligned}$$

$$\begin{aligned}
 & + E (y - a + 1)^2 (y + a)^2 \mathbf{1}_{(y > a^{0.25} + a)}] \\
 & \leq O(a^{2.5}) P \{a^{0.25} + a \geq y > a\} + 4O(a^4) [P(y > a + a^{0.25})]^{1/2} \\
 & = O(a^{1.75}) \tag{7.21}
 \end{aligned}$$

Consequently, by (7.15), (7.17), and (7.21), the desired assertion follows.

Lemma 2.2: Under the above notations, $E \delta_2^2(y) = o(a^2)$

Proof: The proof is similar to that of Lemma 2.1.

Lemma 2.3: Under the above notations, $E \delta_3^2(y) = o(a^2)$

Proof: When $a \geq 2$,

$$\begin{aligned}
 \delta_3^2(y) & \leq 2 \left[y^2 \left(\int_{|\theta| \geq 1} \theta^{2n-1} \exp(-(y - \theta)^2 / 2) d\theta / I \right)^2 \right. \\
 & \quad \left. + y^2 \left(\int_{|\theta| < 1} \theta^{2n-1} \exp(-(y - \theta)^2 / 2) d\theta / I \right)^2 \right] \\
 & \leq 2 \left[y^2 + y^2 \left(\frac{\int_{|\theta| < 1} \theta^{2n-1} \exp(-(y - \theta)^2 / 2) d\theta}{2} \right)^2 \right] \tag{7.22} \\
 & \quad \int_{-2} \theta^{2n} \exp(-(y - \theta)^2 / 2) d\theta
 \end{aligned}$$

Let

$$g(y) = \frac{\int_{|\theta| < 1} \theta^{2n-1} \exp(-(y - \theta)^2 / 2) d\theta}{2} \int_{-2} \theta^{2n} \exp(-(y - \theta)^2 / 2) d\theta$$

Obviously, by the continuity of g , when $|y| \leq 2$, $g(x) \leq c$, a finite constant. And when $y > 2$,

$$\int_{|\theta| < 1} \theta^{2n-1} \exp(-(y - \theta)^2 / 2) d\theta \leq 2 \exp(-(y - 1)^2 / 2)$$

while

$$\int_{-2}^2 \theta^{2n} \exp(- (y - \theta)^2 / 2) d\theta \geq \exp(- (y - 1)^2 / 2)$$

Hence, $|g(x)| \leq 2$, when $x > 2$. Similarly, when $x < -2$, $|g(x)| \leq 2$. Thus, we concluded that

$$\delta_3^2(y) \leq 2 \max(c^2 + 1, 5) y^2$$

As $\frac{y^2}{a^2}$ is uniformly integrable, and so is $\frac{\delta_3^2(y)}{a^2}$. Consequently,

$$E \frac{\delta_3^2(y)}{a^2} \rightarrow 0 \text{ (as } a \rightarrow \infty)$$

The assertion follows.

Proof of Lemma 4.1

Without loss of generality, assume that $\sigma = 1$. Then the likelihood ratio of the density under H_0 and H_1 is

$$L_n = \prod_1^n L_{n,i} \quad (7.23)$$

where

$$L_{n,i} = \exp(-t_n^2/2) [\exp(t_n y_i) + \exp(-t_n y_i)]/2$$

Denote $\phi_{n,i,t_n} = \log L_{n,i}$, then

$$\begin{aligned} \phi_{n,i,t_n} &= -t_n^2/2 + \log[1 + \frac{t_n^2 y_i^2}{2} + \frac{t_n^4 y_i^4}{24} + O_p(t_n^6)] \\ &= -t_n^2/2 + \frac{t_n^2 y_i^2}{2} + \frac{t_n^4 y_i^4}{24} - \frac{t_n^4 y_i^4}{8} + O_p(t_n^6) \end{aligned}$$

Consequently,

$$\frac{\log L_n + n t_n^4/4}{\sqrt{n/2} t_n^2} = \frac{\sum_1^n (y_i^2 - 1) t_n^2/2 - t_n^4 (y_i^4 - 3)/12}{\sqrt{n/2} t_n^2} + O_p(\sqrt{n} t_n^4)$$

By invoking the central limit theorem for i.i.d. case, we conclude that

$$\frac{\log L_n + nt_n^4/4}{\sqrt{n/2} t_n^2} \xrightarrow{L} N(0, 1)$$

under H_0 . Note that

$$\frac{\log L_n - nt_n^4/4}{\sqrt{n/2} t_n^2} = \frac{\sum_1^n (y_i^2 - 1 - t_n^2)/2 - t_n^2(y_i^4 - Ey_i^4)/12 + O(nt_n^4)}{\sqrt{n/2}} + O_P(\sqrt{n} t_n^4)$$

Now, under H_1 ,

$$nE(|y_i^2 - 1 - t_n^2|/\sqrt{n})^4 = O(n^{-1})$$

and

$$nE(|y_i^4 - Ey_i^4|/\sqrt{n})^4 = O(n^{-1})$$

Hence, the Lyapounov's condition holds for the triangular arrays. By triangular array central limit theorem, under H_1 ,

$$\frac{\log L_n - nt_n^4/4}{\sqrt{n/2} t_n^2} \xrightarrow{L} N(0, 1)$$

Consequently, the sum of type I and type II error is

$$P_{H_0}[L_n > 1] + P_{H_1}[L_n \leq 1] = 2 \Phi\left(-\frac{\sqrt{n} t_n^2}{\sqrt{8}}\right)(1 + o(1))$$

Proof of Theorem 4:

The first two results is actually proved by the argument before stating Theorem 4. The third result follows from the inequality

$$I(|t|) \geq I(1) \mathbf{1}_{(|t| \geq 1)} \quad (7.24)$$

Proof of Corollary 4.1:

Take $n_\sigma = \lceil (\sqrt{c} \sigma)^{-\frac{4}{4p-1}} \rceil$. Then,

$$\begin{aligned}
 & (\sum_1^{n_\sigma} j^q) n_\sigma^{-2p} \\
 &= n_\sigma^{q+1-2p} / (q+1) (1 + o(1)) \\
 &= c^{1 - \frac{2q+1}{4p-1}} \sigma^{2 - \frac{2(2q+1)}{4p-1}} / (q+1)
 \end{aligned}$$

Hence, the assertion follows from Theorem 4.

Proof of Theorem 5:

Consider the testing problem

$$H_0: y \sim N(x_1, \sigma^2) \leftrightarrow H_1: y \sim N(x_2, \sigma^2) \quad (7.25)$$

Then, the likelihood ratio is

$$L = \exp\left(\frac{y(x_2 - x_1)}{\sigma^2} - \frac{\|x_2\|^2 - \|x_1\|^2}{2\sigma^2}\right)$$

and the minimum sum of the type I and type II error is

$$\begin{aligned}
 \min_{0 \leq \phi \leq 1} (E_{x_1} \phi(y) + E_{x_2} (1 - \phi(y))) &= P_{x_1}(L > 1) + P_{x_2}(L \leq 1) \\
 &= 2\Phi\left(-\frac{\|x_1 - x_2\|}{2\sigma}\right)
 \end{aligned}$$

where $\Phi(\cdot)$ is the distribution of the standard normal distribution. Let $r = \frac{1}{2} |T(x_1) - T(x_2)|$

be the half of the change of the functional. Then, by the same argument as those in (4.5), we have

$$\begin{aligned}
 \sup_{x \in \Sigma} E_x (\delta(y) - T(x))^2 &\geq \frac{1}{2} r^2 [P_{x_1}(|\delta(y) - T(x_1)| > r) + P_{x_2}(|\delta(y) - T(x_1)| < r)] \\
 &\geq \frac{|T(x_1) - T(x_2)|^2}{4} \Phi\left(-\frac{\|x_1 - x_2\|}{2\sigma}\right)
 \end{aligned}$$

Taking "sup" over $x_1, x_2 \in \Sigma$ subject to $\|x_1 - x_2\|^2 = c\sigma$, we get the desire result.

Proof of Theorem 6

Consider the testing problem (4.2) with $t_n = l_n$, and $n = N_\sigma$. By Lemma 4.1, there is no perfect test between H_0 and H_1 , i.e. the minimum sum of type I and type II error is bounded away from 0. Hence, by the similar algebra as those in (4.5), the half of change of the functional from H_0 to H_1 is a lower bound of estimating $T(x)$. Now when σ is small, by assumption, the change of functional from H_0 to H_1 is at least $Q(x_\sigma)$. Hence, $Q(x_\sigma)$ is a lower rate. As $B_T(c\sigma) = o(Q(x_\sigma))$, we conclude the second result.

Proof of Theorem 7

Without loss of generality, let the supremum over t in the definition of α_T be attained, at t_0 , and the supremum over Δ in the definition of Δ_T be attained, at Δ . Then by definition, it follows the minimax risk for testing between H_0 and H_1 is at least α , i.e.

$$\min_{0 \leq \phi \leq 1} \sup_{x_0 \in \Sigma_T \leq t_0, x_1 \in \Sigma_T \geq t_0 + \Delta} [E_{x_0} \phi + E_{x_1} (1 - \phi)] \geq \alpha \quad (7.26)$$

Now for any estimator δ , and $x_1 \in \Sigma_T \geq t_0 + \Delta$

$$P_{x_1} \{ |\delta(y) - T(x_1)| \geq \Delta/2 \} \geq P_{x_1} \{ |\delta(y) - T(x_0)| < \Delta/2 \}$$

Hence, by (7.26)

$$\begin{aligned} & \sup_{x_0 \in \Sigma_T \leq t_0, x_1 \in \Sigma_T \geq t_0 + \Delta} \max_{x_0, x_1} P_{x_i} \{ |\delta(y) - T(x)| \geq \Delta/2 \} \\ & \geq \sup_{x_0 \in \Sigma_T \leq t_0, x_1 \in \Sigma_T \geq t_0 + \Delta} \frac{1}{2} [P_{x_0} \{ |\delta(y) - T(x_0)| \geq \Delta/2 \} + P_{x_1} \{ |\delta(y) - T(x_0)| < \Delta/2 \}] \\ & \geq \alpha/2 \end{aligned}$$

Thus, the conclusion first result follows. The second result follows from the inequality (7.24)

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