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A NOTE ON THE EVALUATION OF  
THE TOTAL SQUARE INTEGRAL\*

by

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# A NOTE ON THE EVALUATION OF THE TOTAL SQUARE INTEGRAL\*

E. I. Jury\*\*

The purpose of this note is (a) to show the general formulation of the total square integrals in discrete systems and (b) to show for such a formulation we need to expand only (n-1)-order determinant.

Recently a tabulation of the total square integrals which arise in discrete systems have been presented.<sup>1</sup> This tabulation which was carried out for systems up to fourth order is based on the evaluation of the following determinants:

$$I_n = \frac{|\Omega|}{a_0|\Omega|} = \frac{1}{2\pi j} \oint_{\text{unit circle}} \mathcal{F}(z) \mathcal{F}(z^{-1}) z^{-1} dz$$

where  $\Omega$  is the following matrix<sup>†</sup>:

$$\begin{bmatrix} a_0 & a_1 & a_2 & a_3 & \dots & a_n \\ a_1 & a_0+a_2 & a_1+a_3 & a_3+a_4 & \dots & a_{n-1} \\ a_2 & a_3 & a_0+a_4 & a_1+a_5 & \dots & a_{n-2} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ a_n & 0 & 0 & 0 & \dots & a_0 \end{bmatrix}$$

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† It should be noted that when all the poles of  $\mathcal{F}(z)$  are inside the unit circle, this determinant never vanishes.

and  $\Omega_1$  is the matrix formed from  $\Omega$  by replacing the first column by

$$\begin{bmatrix} \sum_{i=0}^n b_i z^2 \\ z \sum b_i b_{i+1} \\ z \sum b_i b_{i+2} \\ \vdots \\ z \sum b_i b_{i+n-1} \\ 2b_0 b_n \end{bmatrix}$$

The function  $\mathcal{F}(z)$  is given by

$$\mathcal{F}(z) = \frac{B(z)}{A(z)},$$

where

$$A(z) = \sum_{r=0}^n a_r z^{n-r}, \quad a_0 \neq 0$$

$$B(z) = \sum_{r=0}^n b_r z^{n-r}.$$

To show the procedure of evaluation, a fifth-degree polynomial is first discussed and then the general results for the n-th degree is stated. For a fifth-degree polynomial the total square integral is given by:

$$I_5 = \frac{1}{2\pi j} \oint_{\text{unit circle}} \frac{B(z)}{A(z)} \frac{B(z^{-1})}{A(z^{-1})} z^{-1} dz$$

where

$$\frac{B(z)}{A(z)} = \frac{b_0z^5 + b_1z^4 + b_2z^3 + b_3z^2 + b_4z + b_5}{a_0z^5 + a_1z^4 + a_2z^3 + a_3z^2 + a_4z + a_5}$$

and

$$I_5 = \frac{|\Omega_1|}{a_0|\Omega|}$$

The matrices  $\Omega$  and  $\Omega_1$  are given by:

$$\Omega^\dagger = \begin{bmatrix} a_0 & a_1 & a_2 & a_3 & a_4 & a_5 \\ a_1 & \underbrace{a_0+a_2}_{e_1} & a_1+a_3 & a_2+a_4 & \underbrace{a_3+a_5}_{e_4} & a_4 \\ a_2 & a_3 & \underbrace{a_0+a_4}_{f_1} & \underbrace{a_1+a_5}_{f_2} & a_2 & a_3 \\ a_3 & a_4 & a_5 & a_0 & a_1 & a_2 \\ a_4 & a_5 & 0 & 0 & a_0 & a_1 \\ a_5 & 0 & 0 & 0 & 0 & a_0 \end{bmatrix}$$

<sup>†</sup> For ease of calculation and to identify certain terms certain entries in the matrix have been labeled as indicated above.

$$\Omega_1^\dagger = \begin{bmatrix} b_0^2 + b_1^2 + b_2^2 + b_3^2 + b_4^2 + b_5^2 & a_1 & a_2 & a_3 & a_4 & a_5 \\ \underbrace{2(b_0 b_1 + b_1 b_2 + b_2 b_3 + b_3 b_4 + b_4 b_5)}_{B_1} & \underbrace{a_0 + a_2}_{e_1} & \underbrace{a_1 + a_3}_{e_2} & \underbrace{a_2 + a_4}_{e_3} & \underbrace{a_3 + a_5}_{e_4} & a_4 \\ \underbrace{2(b_0 b_2 + b_1 b_3 + b_2 b_4 + b_3 b_5)}_{B_2} & a_3 & \underbrace{a_0 + a_4}_{f_1} & \underbrace{a_1 + a_5}_{f_2} & a_2 & a_3 \\ \underbrace{2(b_0 b_3 + b_1 b_4 + b_2 b_5)}_{B_3} & a_4 & a_5 & a_0 & a_1 & a_2 \\ \underbrace{2(b_0 b_4 + b_1 b_5)}_{B_4} & a_5 & 0 & 0 & a_0 & a_1 \\ \underbrace{2b_0 b_5}_{B_5} & 0 & 0 & 0 & 0 & a_0 \end{bmatrix}$$

The numerator determinant is given by:

$$|\Omega_1| = a_0 B_0 Q_0 - a_0 B_1 Q_1 + a_0 B_2 Q_2 - a_0 B_3 Q_3 + a_0 B_4 Q_4 - B_5 Q_5$$

where the  $Q_i$ 's are given as follow:

$$Q_0 = \begin{vmatrix} e_1 & e_2 & e_3 & e_4 \\ a_3 & f_1 & f_2 & a_2 \\ a_4 & a_5 & a_0 & a_1 \\ a_5 & 0 & 0 & a_0 \end{vmatrix}, \quad Q_1 = \begin{vmatrix} a_1 & a_2 & a_3 & a_4 \\ a_3 & f_1 & f_2 & a_2 \\ a_4 & a_5 & a_0 & a_1 \\ a_5 & 0 & 0 & a_0 \end{vmatrix},$$

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† See note page 3.

$$Q_2 = \begin{vmatrix} a_1 & a_2 & a_3 & a_4 \\ e_1 & e_2 & e_3 & e_4 \\ a_4 & a_5 & a_0 & a_1 \\ a_5 & 0 & 0 & a_0 \end{vmatrix}$$

$$Q_3 = \begin{vmatrix} a_1 & a_2 & a_3 & a_4 \\ e_1 & e_2 & e_3 & e_4 \\ a_3 & f_1 & f_2 & a_2 \\ a_5 & 0 & 0 & a_0 \end{vmatrix}$$

$$Q_4 = \begin{vmatrix} a_1 & a_2 & a_3 & a_4 \\ e_1 & e_2 & e_3 & e_4 \\ a_3 & f_1 & f_2 & a_2 \\ a_4 & a_5 & a_0 & a_1 \end{vmatrix}$$

$$Q_5 = \begin{vmatrix} a_1 & a_2 & a_3 & a_4 & a_5 \\ e_1 & e_2 & e_3 & e_4 & a_4 \\ a_3 & f_1 & f_2 & a_2 & a_3 \\ a_4 & a_5 & a_0 & a_1 & a_2 \\ a_5 & 0 & 0 & a_0 & a_1 \end{vmatrix}$$

It is noticed from  $Q_5$  that one has to expand a fifth-order determinant; however, the following relationship exists which reduces the order. Expanding  $Q_5$  along the last column,

$$Q_5 = a_5 \begin{vmatrix} e_1 & e_2 & e_3 & e_4 \\ a_3 & f_1 & f_1 & a_2 \\ a_4 & a_5 & a_0 & a_1 \\ a_5 & 0 & 0 & a_0 \end{vmatrix} - a_4 \begin{vmatrix} e_1 & e_2 & e_3 & e_4 \\ a_3 & f_1 & f_2 & a_2 \\ a_4 & a_5 & a_0 & a_1 \\ a_5 & 0 & 0 & a_0 \end{vmatrix} + \dots \text{ so on.}$$

one obtains

$$Q_5^\dagger = a_5 Q_0 - a_4 Q_1 + a_3 Q_2 - a_2 Q_3 + a_1 Q_4$$

and hence,

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† The author is grateful to Dr. Paul LeFevre of Paris, France, for pointing this relationship for the fourth and third order cases, which can be generalized to any order. For numerical calculation the above relationship is quite useful.

$$\begin{aligned}
|\Omega| &= (a_0 B_0 - a_5 B_5) Q_0 - (a_0 B_1 - a_4 B_5) Q_1 \\
&\quad + (a_0 B_0 - a_3 B_5) Q_2 - (a_0 B_3 - a_2 B_5) Q_3 \\
&\quad + (a_0 B_4 - a_1 B_5) Q_4
\end{aligned}$$

by replacing B's by a's in  $|\Omega|$ , one obtains

$$\begin{aligned}
|\Omega| &= (a_0^2 - a_5^2) Q_0 - (a_0 a_1 - a_4 a_5) Q_1 + (a_0 a_2 - a_3 a_5) Q_2 \\
&\quad - (a_0 a_3 - a_2 a_5) Q_3 + (a_0 a_4 - a_1 a_5) Q_4 .
\end{aligned}$$

Hence,

$$\begin{aligned}
I_5 &= \frac{(a_0 B_0 - a_5 B_5) Q_0 - (a_0 B_1 - a_4 B_5) Q_1 + (a_0 B_2 - a_3 B_5) Q_2 \\
&\quad - (a_0 B_3 - a_2 B_5) Q_3 + (a_0 B_4 - a_1 B_5) Q_4}{a_0 [(a_0^2 - a_5^2) Q_0 - (a_0 a_1 - a_4 a_5) Q_1 + (a_0 a_2 - a_3 a_5) Q_2 \\
&\quad - (a_0 a_3 - a_2 a_5) Q_3 + (a_0 a_4 - a_1 a_5) Q_4]} .
\end{aligned}$$

For evaluating  $I_5$ , it appears that one has to evaluate the determinants  $Q_0$ ,  $Q_1$ ,  $Q_2$ ,  $Q_3$ , and  $Q_4$ . However by using the following artifice, one need only to evaluate the last one, i. e.,  $Q_4$ . All the others can be readily obtained by a certain substitution as follows:

1. Expand  $Q_4$  by labeling its entries as follows.

$$Q'_4 = \begin{vmatrix} b_1 & b_2 & b_3 & b_4 \\ c_1 & c_2 & c_3 & c_4 \\ d_3 & f_1 & f_2 & d_2 \\ k_4 & k_5 & k_0 & k_1 \end{vmatrix}$$



From  $Q'_4$ , one obtains  $Q'_3$  by using the following substitution as noticed from  $Q_3$ ,

$$k_4 = a_5, \quad k_5 = 0, \quad k_0 = 0, \quad k_1 = a_0.$$

From  $Q'_3$ , one obtains  $Q'_2$  as follows:

$$\text{let, } d_3 = a_4, \quad f_1 = a_5, \quad f_2 = a_0, \quad d_2 = a_1.$$

Similarly  $Q'_1$  is obtained from  $Q'_2$  as follows,

$$c_1 = a_3, \quad c_2 = f_1, \quad c_3 = f_2, \quad c_4 = a_2.$$

Finally,  $Q_0$  is obtained from  $Q'_1$  by letting

$$b_1 = e_1, \quad b_2 = e_2, \quad b_3 = e_3, \quad b_4 = e_4.$$

2. By relabeling the entries of  $Q'_r$  to coincide with  $Q_r$  one obtains all the required  $Q_r$ 's.

This process can be readily generalized for any order system which requires the evaluation of only one  $(n-1)$ -order determinant.

Generalizing the above procedure, to obtain

$$a_0 I_n = \frac{\begin{aligned} &[(a_0 B_0 - a_n B_n) Q_0 - (a_0 B_1 - a_{n-1} B_n) Q_1 + \dots \\ &+ (-1)^{n-1} (a_0 B_{n-1} - a_1 B_n) Q_{n-1}] \end{aligned}}{\begin{aligned} &[(a_0^2 - a_n^2) Q_0 - (a_0 a_1 - a_{n-1} a_n) Q_1 + (a_0 a_2 - a_{n-2} a_n) + \dots \\ &+ (-n)^{n-1} (a_0 a_{n-1} - a_1 a_n) Q_{n-1}] \end{aligned}}$$

where

$$B_0 = \sum_{i=0}^n b_i^2$$

and

$$B_r = 2 \sum_{i=0}^n b_i b_{i+r} \quad r = 1, 2, \dots, n.$$

Furthermore, the  $Q_r$ 's for  $r = 0, \dots, (n-1)$  are  $(n-1)$  by  $(n-1)$  determinants, obtained as follows:

$a_0$	$a_1$	$a_2$	$a_3$	$\dots$	$a_{n-2}$	$a_{n-1}$	$a_n$
$a_1$	$a_2+a_0$	$a_3+a_1$	$a_4+a_2$	$\dots$	$a_{n-1}+a_{n-3}$	$a_n+a_{n-2}$	$a_{n-1}$
$a_2$	$a_3$	$a_4+a_0$	$a_5+a_1$	$\dots$	$a_n+a_{n-4}$	$0+a_{n-3}$	$a_{n-2}$
$a_r$	$a_{r+1}$	$\dots$	$\dots$	$\dots$	$a_{n-r-1}$	$a_{n-r}$	$a_{n-r}$
$a_{n-1}$	$a_n$	0	$\dots$	$\dots$	0	$0+a_0$	$a_1$
$a_n$	0	0	$\dots$	$\dots$	0	0	$a_0$

By deleting the  $r$ -th row and the  $n$ -th row and by deleting the first and  $n$ -th columns, the remaining rows and columns give  $(n-1)$ -order,  $Q_r$ , determinant.

As shown for the fifth-order case, we can obtain all the  $Q_r$ 's by expanding only the matrix of the  $Q_{n-1}$ . Therefore, for obtaining the value of  $I_n$  we need to expand only one  $(n-1)$ -order determinant. If the coefficients are given in numerical value, then we have to calculate all the  $Q_r$ 's.

#### REFERENCE

1. E. I. Jury, Theory and Application of the z-transform method, John Wiley and Sons, Inc., New York, 1964., Ch. 4 and Table III.